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Modelling selection, drift, dispersal and their interactions in the community assembly of Amazonian soil mites

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Abstract

Three processes can explain contemporary community assembly: natural selection, ecological drift and dispersal. However, quantifying their effects has been complicated by confusion between different processes and neglect of expected interactions among them. One possible solution is to simultaneously model the expected effects of each process within species, across communities and across species, thus providing more integrative tests of ecological theory. Here, we used generalized linear mixed models to assess the effects of selection, drift and dispersal on the occurrence probability of 135 soil oribatid mite species across 55 sites over an Amazonian rainforest landscape (64 km²). We tested for interactions between process-related factors and partitioned the explained variation among them. We found that occurrence probability (1) responded to soil P content and litter mass depending on body size and reproductive mode (sexual or parthenogenetic), respectively (selection); (2) increased with community size (drift); and (3) decreased with distance to the nearest source population, and more so in rare species occurrence probability. However, most of the variation was attributable to dispersal limitation (55%). Our results challenge the seldom-tested theoretical prediction that ecological processes should interact. Rather, they suggest that dispersal limitation overrides the signatures of drift and selection at the landscape level, thus rendering soil microarthropod species ecologically equivalent and possibly contributing to the maintenance of metacommunity diversity.

Keywords Community structure · Ecological niche · Environmental filtering · Functional traits · Dispersal limitation

Introduction

Community assembly can be understood in terms of four higher-level processes: natural selection, ecological drift, dispersal, and speciation (Hanson et al. 2012; Vellend 2016).

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Over observable periods, speciation is generally negligible, and meta-analyses have suggested a predominant role for environmental selection over dispersal limitation (Cottenie 2005; Hanson et al. 2012; Soininen 2016). However, the standard variance partitioning used in metacommunity analyses assumes additive effects for environmental and spatial predictors despite the theory predicting ecological processes should interact (Hanson et al. 2012; Vellend 2016; Siqueira et al. 2020). Further, drift and dispersal have often been lumped as "stochastic" or "neutral" processes that contrast with "deterministic" niche processes (i.e. selection), which underestimates that drift and dispersal should have different effects (Hanson et al. 2012; Vellend et al. 2014). More generally, stochasticity (random variation) is not the same as neutrality (similar mean fitness across species), and the same process can have stochastic and deterministic components (e.g. selection driven by environmental stochasticity). Hence, there remain important knowledge gaps about the mode and strength with which ecological processes shape natural metacommunities.

One way of approaching this issue is to use hierarchical models to estimate species-specific relationships while accounting for their dependence on species traits and community features so that the predicted independent and interactive effects of ecological processes can be more easily quantified (Ovaskainen and Soininen 2011; Sydenham et al. 2019). In general, species are adapted to certain environmental conditions, and this is reflected in their traits. Accordingly, the environmental response of species occurrence probability should depend on their traits, reflecting natural selection (Keddy 1992). However, species may also be ecologically equivalent, i.e. perform similarly along environmental gradients on average, so that their local occurrence probability depends more on randomness in births and deaths than on fitness differences (i.e. ecological drift) (Hubbell 2001). If so, occurrence probability should decrease as community size (i.e. total number of individuals) decreases, due to more frequent random extinction (Hubbell 2001; Vellend 2016). When communities are linked by dispersal, the immigration rate is expected to decrease with distance to the nearest source population, so that species occurrence probability should decline similarly (i.e. dispersal limitation) (MacArthur and Wilson 1967). Further, for a given dispersal rate, dispersal limitation should increase as species commonness (i.e. number of individuals in the metacommunity) decreases, as rarer species have fewer dispersers and, thus, lower chance of reaching a given site over a given period (Hubbell 2001). Likewise, dispersal limitation also could depend on species traits (Soininen 2016).

Processes themselves can interact variously depending on model details. Generally, though, stronger drift in smaller communities should weaken selection effects by introducing noise in species responses to trait×environment interactions (Siqueira et al. 2020). Likewise, high dispersal rates closer to dispersal sources may weaken selection effects by increasing species occurrence in suboptimal habitats ("mass effect"; Shmida and Wilson 1985), or actually strengthen them by mixing species and facilitating species sorting (Ron et al. 2018). Lastly, dispersal and drift can also interact: local occurrence probability depends on the product between species commonness in the metacommunity and local community size, so that common species benefit more from increases in the latter (Hubbell 2001; Waller et al. 2018).

Smaller organisms are expected to be more affected by selection than by drift or dispersal limitation due to their higher abundance and passive dispersal (Kaspari et al. 2010; Soininen 2016). By contrast, studies on terrestrial microarthropods such as mites and springtails (<2 mm) have often found much variation in species composition that is unrelated to the environment (Borcard and Legendre 1994; Caruso et al. 2012; Gao et al. 2014; Widenfalk et al. 2016; Magilton et al. 2019; Zinger et al. 2019). Yet, such studies have typically focused on very small spatial

grains (soil cores $< 100 \text{ cm}^2$) and extents (< 1 km, often much less), where smaller community size may increase the relative importance of drift, even if absolute community size is large (Fodelianakis et al. 2021). While there is some evidence for stronger effects of selection and dispersal limitation over larger spatial extents (Mumladze et al. 2013; Caruso et al. 2019), few studies with reasonable sampling design have addressed this issue at the landscape level (1-10 km) (e.g. Ingimarsdóttir et al. 2012), and it is unclear the extent to which dispersal effectively connects site-level communities and modifies the effects of selection and drift. While there is strong spatial autocorrelation in soil fauna from tenths to a few hundred meters (Ettema and Wardle 2002; Minor 2011), passive dispersal through wind, water currents or transport by larger animals (Costa et al. 2013; Schuppenhauer et al. 2019) may connect communities over much larger ranges.

Here, we investigated the relative importance of selection, drift, and dispersal in the site-level community assembly of oribatid mites, a numerically dominant group of soil microarthropods. We used data from a unique, large sampling effort over an Amazonian rainforest landscape (1100 soils cores across 55 sites over 64 km^2). Two traits have been highlighted as mediators of oribatid environmental responses: (1) body size, with larger species possibly being favoured by soils with larger interstices, or more resources given higher metabolic demand (Brückner et al. 2018); and (2) reproductive mode (sexual or parthenogenetic), as the prevalence of parthenogens varies widely across local oribatid communities, with parthenogens possibly better coping with disturbance through faster reproduction while suffering stronger resource limitation due to clonal competition (Maraun et al. 2019). Body size may also affect dispersal capacity, although the relationship is seemingly complex and hard to predict (Soininen 2016; Schuppenhauer et al. 2019).

To test for the predicted effects of ecological processes, we modelled species occurrence probability as a function of: (1) the interactions body size \times environmental variables and reproductive mode × environmental variables, representing selection; (2) community size, representing ecological drift; and (3) the interactions commonness x distance-from-source and body size x distancefrom-source, representing dispersal. We also tested for the expected effects of interactions between selection and drift (trait × environment × community size), selection and dispersal (trait × environment × distance) and drift and dispersal (community size x commonness). Then, we partitioned the variation in species occurrence explained by significant predictors. We expected stronger effects of dispersal limitation and selection over the landscape, with weaker effects of drift and selection between nearby sites due to higher dispersal rates.

Materials and methods

Study site

The data used in this study were obtained as part of the Brazilian Program for Biodiversity Research (PPBio) in Reserva Ducke (Pequeno et al. 2021), a large reserve of primary tropical rainforest (10×10 km) in Manaus, northern Brazil (2°57' S, 59°56' W) (Costa and Magnusson 2010). The reserve is managed by the National Institute for Amazonia Research (INPA). Local terrain is traversed by a dense drainage network, where bottomlands have almost pure sands and uplands have clayish soils (soil clay content > 70%). Bottomlands are dominated by ferns, herbs and arborescent palms, whereas in uplands, trees establish a closed canopy with some individuals reaching 40-45 m, and the undergrowth is dominated by stemless palms. Mean daily temperature and mean annual rainfall during 1992-2002 were 26.7 °C and 2479 mm, respectively, with a relatively dry season (less than 100 mm) from July to September (Coordination for Research on Climate and Hydric Resources, INPA, unpublished data).

Mite data

Mite sampling was carried out from March 18 to May 13, 2002. Mites were collected from 55 sites distributed over a grid in the reserve, with at least 1 km between them (Fig. 1). On each site, one 250-m transect was established along a topographic contour lines, to minimize environmental variation within it (Costa and Magnusson 2010). Then, one soil core $(3.5 \text{ cm} \times 3.5 \text{ cm} \times 5 \text{ cm})$ was sampled each 12.5 m along the transect, with 20 cores per transect and 55 sites \times 20 cores = 1100 cores overall. Within-site soil cores thus provided a representative sample of the



Fig. 1 Geographic disposition of sampling sites across an Amazonian rainforest landscape in Manaus, Northern Brazil

local, site-level community (Ettema and Wardle 2002; Minor 2011), which was the sampling unit of the study. To reduce the large sample processing load, each four consecutive soil cores within transects were combined as a compound soil sample. Compound samples were kept in plastic containers and transported to the Laboratory of Systematics and Ecology of Terrestrial Arthropods at INPA's campus in Manaus, where animals were extracted using a modified Berlese-Tullgren apparatus (Franklin and de Morais 2006). Samples were gradually heated from 28 to 45 °C until they were completely dry, which took from six to seven days. Extracted animals were preserved in glass vials containing 4% formaldehyde solution.

All adult oribatid mites were sorted into morphospecies and identified whenever possible using taxonomic keys (Online Resource 1). Identification proceeded by clarifying specimens with lactic acid, followed by temporary slide-mounting and examination under a compound microscope. Immatures were not considered but represented only 8% of extracted individuals. Voucher specimens were deposited in the Entomological Collection of INPA.

We estimated the mean body mass of each sampled species by measuring 1–15 individuals of each sampled species, depending on their abundance. For each individual, body length and width (μ m) were measured under a microscope, and body mass (μ g) was predicted using a well-established allometric equation ($R^2 = 0.98$; Caruso and Migliorini 2009):

$$Mass = -17.17 + 3.0\log(length + width)$$
(1)

Then, the mean body mass was calculated for each species.

Species reproductive mode (sexual or parthenogenetic) was inferred using published records (Maraun et al. 2019). In oribatid mites, parthenogenesis is estimated to occur in nearly 10% of species (Norton and Palmer 1991). When present, it is obligatory and thelytokous, i.e. all individuals are diploid female clones produced from unfertilized eggs (Heethoff et al. 2009). When a species' reproductive mode was unknown (i.e. morphospecies with a single individual), it was inferred from closely related species, if part of a taxonomic group that is not known to vary in reproductive mode. Otherwise, the species was assumed to be sexual.

Overall, 2046 adult individuals in 135 (morpho)species were found, of which 898 individuals in 22 species were parthenogenetic, representing only 16% of the species but 44% of the individuals (Online Resource 1, Table S1, Fig. S1). There was no relationship between body mass and reproductive mode (Linear Mixed Model with taxonomic ranks as nested random factors, n = 135, t = 0.96, P = 0.34; Online Resource 1, Fig. S2). Data were obtained on soil texture (clay content, in %), soil contents of water (%) and nutrients (C, N and P, in $g kg^{-1}$) and litter dry mass (g). Litter dry mass was measured during mite surveys by marking 50×50 cm squares along transects, one each 50 m, within which all litter was harvested. Litter samples were transported to the laboratory in plastic containers and dried to constant weight. Further, in each transect, six soil cores (one each 50 m) were collected to a depth of 5 cm. Soil cores were pooled in a plastic container and transported to INPA for granulometric analysis, and to the Brazilian Agricultural Research Corporation (EMBRAPA), also in Manaus, for nutrient analyses. Soil samples were oven-dried, cleaned of stones and roots, and passed through a 2 mm sieve. Soil granulometry was determined using the hydrometer method (clay: <0.002 mm; silt: 0.002–0.05 mm; sand: 0.05-2 mm). As clay and sand contents were highly correlated (r = -0.99) and silt content was negligible, we used clay to describe soil texture. Total organic carbon was measured by wet oxidation, using acid dichromate solution followed by titration with 0.5 N FeSO₄ and o-phenalphthroline. Total nitrogen was estimated using the wet oxidation (Kjeldahl method), by converting organic N to ammonium (NH4+) for measurement. Available phosphorus was estimated using the ammonium molybdate-ascorbic acid method, by reading the blue complex formed at 712 nm under a spectrophotometer. Soil water content was obtained by comparison between the wet and dry weights of soil samples. Soil and litter measurements were averaged by site.

Statistical analyses

We built a generalized linear mixed model that combines species-specific models in a common model for all species by assuming that species responses to a common predictor depend on species traits and features of local communities. By doing so, we can simultaneously test for relationships within species, across species, and across local communities. This approach also overcomes the difficulty in separately modelling rare species, by gaining information from the other species (Ovaskainen and Soininen 2011), and has been shown to reliability identify prevailing assembly processes in simulated metacommunities (Ovaskainen et al. 2019; Sydenham et al. 2019). Here, we extended this approach by including model terms representing predicted interactions among all three ecological processes, and partitioning the variation explained by them (see below). Because of the large number of parameters of interest, we divided the analysis in two parts: we (1) built a global model testing for the separate effects of drift, selection, and dispersal, and simplified it by excluding parameters that were not statistically supported; (2) created three alternative versions of the simplified model representing the interactions between drift and selection, selection and dispersal, and drift and dispersal, and determined the most supported model among these four.

We first concatenated species occurrences (presence or absence) into a single occurrence variable with 135 spe $cies \times 55$ sites = 7425 observations. Then, this variable was modelled in relation to the predictors of interest, assuming binomial errors and complementary log-log link function to account for asymmetric, sigmoid response curves (Zuur et al. 2009), and "species" and "site" as random factors to account for autocorrelation within species and sites, respectively. To test for selection, we included interactions between species traits (body mass and reproductive mode) and environmental variables. Because we had six environmental variables, there were 12 possible trait × environment interactions. To reduce the number of parameters, we summarized environmental variables using Principal Component Analysis (PCA), with soil P log-transformed to account for its skewed distribution. PCA revealed three major environmental gradients: one representing soil texture and organic matter (C and N) (PC1); one representing soil P (PC2); and another representing litter mass (PC3) (Table 1). Thus, we used these three principal components in body mass × PC and reproductive mode \times PC interactions (six interactions). To test for drift, we included community size (total number of individuals in a site) as a predictor. To test for dispersal limitation, we calculated species commonness (total number of individuals in the metacommunity) and the Euclidian distance between each site and the nearest site occupied by the species. Then, we included commonness × distance and body mass × distance interactions as predictors. Community size and species commonness were log-transformed to account for their highly skewed distributions. All numeric predictors were scaled to zero mean and unit variance, and parameters were estimated by maximum likelihood.

When a species occurred at a single site, either the nearest occupied site was outside the sampled area (and its distance was unknown) or it was the single site itself (and the

 Table 1
 Principal Component Analysis (PCA) of environmental variables used in this study

Variable	Range	$r_{\rm PC1}(52\%)$	$r_{\rm PC2}(20\%)$	r _{PC3} (16%)
Soil clay (%)	2-87	0.49	- 0.27	0.25
Soil water (%)	12–65	0.46	0.22	- 0.09
Soil C (g kg ⁻¹)	0.73-7.30	0.48	0.28	- 0.15
Soil N (g kg ⁻¹)	0–13	0.52	0.13	- 0.16
log Soil P (g kg ⁻¹)	15–79	- 0.22	0.77	- 0.29
Litter dry mass (g)	131-482	0.02	0.42	0.89

All variables are site averages (n=55). r_{PC} is the correlation between the variable and ordination scores. Numbers in brackets indicate the variance proportion explained by each axis

distance should be zero). We ran the global model including and excluding such species and found similar results (Table 2; Online Resource 1, Table S2), so we report the analysis including all species. The global model was simplified by excluding non-supported interactions (P > 0.05) and refitting the model to test for independent effects, which were similarly excluded if not supported.

Having the simplified model, we tested for an interaction between drift and selection by adding community size \times trait \times PC interactions to the simplified model. Likewise, to test for an interaction between selection and dispersal, we added distance \times trait \times PC interactions. To test for an interaction between drift and dispersal, we included a community size \times commonness interaction in the simplified model. These three models, along with the simplified model assuming independent effects, were compared using the Bayesian Information Criterion (BIC), and the model with the lowest BIC was judged the most supported.

We assessed the amount of variation explained by the final model using the marginal (R_m^2) and conditional coefficients of determination (R_c^2) , which measure the variation explained by predictors vs. predictors plus random factors in GLMMs, respectively (Nakagawa and Schielzeth 2013). Then, we decomposed the marginal R^2 into fractions

 Table 2
 Generalized linear mixed model of oribatid mite occurrence probability

Process	Predictor	Coefficient	z	Р
	Intercept	- 2.89	_	_
Selection	PC1	0.063	0.905	0.366
	PC2	- 0.081	1.094	0.274
	PC3	- 0.197	2.545	0.011
	log Mass	- 0.05	- 0.708	0.479
	Mode	- 0.023	- 0.238	0.812
	log Mass×PC1	- 0.03	- 0.801	0.423
	log Mass×PC2	0.126	- 3.246	0.001
	log Mass×PC3	- 0.011	0.279	0.78
	Mode×PC1	- 0.051	- 0.638	0.523
	Mode×PC2	0.099	- 1.177	0.239
	Mode×PC3	0.234	- 2.744	0.006
Drift	log Community size	0.598	14.339	< 0.001
Dispersal	Distance	- 0.743	- 8.289	< 0.001
	log Commonness	1.164	14.213	< 0.001
	log Commonness×dis- tance	0.362	3.824	< 0.001
	log Mass × distance	- 0.049	- 0.563	0.573

Models assumed binomial errors, complementary log–log link, and "site" and "species" as random intercepts (n=55 sites×135 species=7425 observations). All numerical predictors were scaled to zero mean and unit variance; reproductive mode was coded as 0 (parthenogenetic) or 1 (sexual). Bold numbers indicate statistically significant effects (P < 0.05)

explained by separate predictor terms using hierarchical partitioning (Chevan and Sutherland 1991). If there were interactions among drift, selection and dispersal, we computed the fraction explained by the interaction (i.e. sum of fractions explained by model terms related to both processes); otherwise, we computed fractions for each process separately. Predictor effects were visualized using conditional plots (Breheny and Burchett 2017).

Our models assumed no residual correlation among sites and among species. This is reasonable because spatial proximity among sites was modelled directly, and because species interactions that could drive microarthropod species correlations independent of their measured environmental responses occur at much finer spatial resolutions (Ettema and Wardle 2002), which should erase their statistical signal (Thuiller et al. 2015). We validated both assumptions by extracting Pearson residuals (on link scale) and (1) creating a spatial correlogram of such residuals using Moran's I, and (2) applying PCA to species residuals to sequentially test PCs (from PC1 onwards) for significant information content using permutation tests, until the first non-significant PC was found (Dray 2008). If species residuals were generally correlated, their shared variation should allow reducing their dimensionality. As expected, there was no evidence for either spatial (Online Resource 1, Fig. S3) or species correlation in residuals (P = 0.30 for PC1). All computations were performed in R 3.6.3 (Team RC 2020), with aid of packages "glmmTMB" (Brooks et al. 2017), "MuMIn" (Barton 2019), "ncf" (Bjornstad 2020), "ade4" (Bougeard and Dray 2018) and "visreg" (Breheny and Burchett 2017).

Results

The global model revealed that species occurrence probability was related to predictors representing selection, drift and dispersal limitation (Table 2). Model simplification revealed that PC1 had no effect whatsoever (z=0.550, P=0.582), so this variable was excluded from the simplified model. Comparison among the simplified model and alternative models including pairwise interactions between selection, drift and dispersal revealed stronger support for the simplified model (Table 3; Online Resource 1, Table S3).

According to the best model, species occurrence probability depended on trait×environment interactions: P-rich soils favoured larger over smaller species (Fig. 2a), whereas sites with more litter selected against parthenogenetic species (Fig. 2b). Second, occurrence probability increased with community size (Fig. 2c). Third, occurrence probability decreased with distance to the nearest source, with rare species reaching relatively low occurrence probability farther from the source faster (Fig. 2d). This model explained 67% of the variation in species occurrence probability, all of Table 3Comparison of
generalized linear mixed models
on oribatid mite occurrence
probability using the Bayesian
Information Criterion (BIC)

Model	Model notation	BIC
Simplified	log Mass×PC2+Mode×PC3+ Community size+ Commonness×Distance	4097.427
Dispersal × drift	log Mass × PC2 + Mode × PC3 + Commonness × Community size + Commonness × Distance	4102.883
Selection × drift	log Mass × PC2 × Community size + Mode × PC3 × Com- munity size + Commonness × Distance	4144.686
Selection × dispersal	log Mass × PC2 × Distance + Mode × PC3 × Distance + Community size + Commonness × Distance	4147.470

Models assumed binomial errors, complementary log-log link, and "site" and "species" as random intercepts (n=55 sites $\times 135$ species = 7425 observations). The simplified model included only the significant interactions in Table 1 plus their lower-order terms; remaining models included additional terms representing pairwise interactions between ecological processes (highlighted in bold). Variables were coded as in Table 1. Model notation omits intercepts and lower-order interaction terms for clarity

Fig. 2 Effects of selection (**a**, **b**), drift (**c**) and dispersal limitation (**d**) on oribatid mite occurrence probability. Lines represent means predicted by the best generalized linear mixed model, which assumed binomial errors, complementary log-log link, and "site" and "species" as random intercepts (n = 55 sites $\times 135$ species = 7425 observations). Coloured bands represented 95% confidence intervals. Upper and bottom tick marks represent presence and absence, respectively. Conditional plots show the effect of each predictor or interaction while holding other predictors at their medians, and sexual species for reproductive mode. Species body mass and commonness were divided as above or below their medians to facilitate visualization



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which was accounted for by predictors only $(R_m^2 = R_c^2)$. Hierarchical partitioning revealed that model terms representing dispersal limitation explained most of this variation, with drift- and particularly selection-related terms contributing much less (Fig. 3).

Discussion

Our analysis revealed clear patterns in the occurrence probability of oribatid mite species that were consistent with the expected effects of selection, drift and dispersal on community assembly. However, most of the variation in occurrence probability was attributable to dispersal limitation, suggesting this is the dominant process shaping community composition across sites over the landscape. Further, there was no evidence for the predicted interactions between the effects of selection, drift and dispersal, supporting the common assumption of additive effects.

The decline in occurrence probability with increasing distance to nearest source reached a "floor" only after a few kilometres (Fig. 2d), suggesting that communities are relatively well connected by dispersal up to this distance. This is consistent with the ease of passive dispersal in soil microarthropods (Costa et al. 2013; Schuppenhauer et al. 2019) and with similar findings from a contrasting, glacial landscape (Ingimarsdóttir et al. 2012). However, the decay in occurrence probability with increasing distance to source was stronger in rarer species (Fig. 2d), as predicted by neutral models: rarer species are less likely to reach farther sites over a given period due to fewer migrants (Hubbell 2001). As the distance to nearest source explained much of the variation in occurrence probability independently of environmental predictors, species may often occur in suboptimal habitats (i.e. mass effect; Shmida and Wilson 1985).

Lower species occurrence probability in smaller communities is consistent with ecological drift: given that births and deaths are not completely predictable from traits (i.e. demographic stochasticity), and that communities are finite, species will be more likely to go extinct in communities with fewer individuals, thereby decreasing their occurrence probability (MacArthur and Wilson 1967; Hubbell 2001; Vellend 2016). For instance, this is the reason for the wellknown species-area relationship in Island Biogeography Theory. Although soil arthropods can reach high densities and our site-level communities were aggregates of 20 soil cores, their size ranged from a few to around 140 individuals only (Fig. 2c), which is within the range over which drift has been found to have significant effects in simulated communities (Hubbell 2001; Vellend 2016). Yet, drift has been demonstrated even in bacterial communities of millions of cells per litre (Fodelianakis et al. 2021). Thus, the relevant question is not whether drift occurs, but how much it affects community structure compared to other processes, namely selection and dispersal.

Most metacommunity analyses of soil macroarthropods focus on rather small spatial grains (e.g. 10 cm) and extents (<1 km), and often find that most variation in community structure is unrelated to environment or space (Caruso et al. 2012; Gao et al. 2014; Magilton et al. 2019; Zinger et al. 2019). While part of this unexplained variation is probably sampling error, it might also reflect the relatively stronger effect of drift in fine-grained communities. By contrast, our results point to a much weaker effect of drift relative to dispersal limitation, which is consistent with the larger spatial grain and extent analyzed here.

There were detectable trait × environment interactions underlying species occurrence probability, consistent with selection. Occurrence probability increased with soil P content for larger species but decreased for smaller species. P strongly limits detrital food webs in lowland tropical forests (Camenzind et al. 2018). Further, P total amount increases while P content decreases with body size in arthropods (Woods et al. 2004). On the one hand, this suggests that P limits larger species simply due to their higher wholebody nutritional reqruiements. On the other hand, species may compete differently for P as function of their size, e.g. smaller species may better forage for P-rich foods (Woods et al. 2004) and thus perform better under low P (Fig. 2a). Likewise, occurrence probability changed little with litter mass in sexual species and decreased in parthenogenetic species. Assuming that most soil oribatid mites are fungivores (Heethoff et al. 2009; Potapov et al. 2019), litter should mainly provide a habitat for mites. Hence, less litter may provide less shelter, e.g. against predators (Wilson 2005). Parthenogens are thought to reproduce faster by dispensing with males and mating, and may be favoured when mortality is high (Maraun et al. 2019), e.g. in more exposed soil.

Regardless of the precise mechanisms driving trait×environment interactions, the low variation explained by them suggests that species were largely distributed as if they were ecologically equivalent, i.e. had similar performance under local environmental conditions (Shmida and Wilson 1985). Ecological equivalence is the key assumption of neutral models of community assembly, as compared to niche models (Hubbell 2001; Vellend 2016). Ecological equivalence is probably an unrealistic assumption in general, given widespread evidence for niche partitioning in plants (Johnson et al. 2017) and animals, including soil fauna (Potapov et al. 2019). However, dispersal limitation can reduce cooccurrence among species that differ in performance when together, thereby delaying competitive exclusion to levels compatible with ecological equivalence (Munoz and Huneman 2016). This might explain why trait \times environment



Fig. 3 Hierarchical partitioning of variation explained by ecological processes under the best generalized linear mixed model for oribatid mite occurrence probability, which assumed binomial errors, complementary log–log link, and "site" and "species" as random intercepts (n=55 sites × 135 species = 7425 observations). Partitioning was based on the marginal coefficient of determination (R^2_m)

interactions, although supported, only weakly explained occurrence probability.

Our results challenge theoretical predictions that ecological processes should interact in community assembly (Hanson et al. 2012; Vellend et al. 2014; Vellend 2016; Ron et al. 2018). Indeed, the few experimental studies that explicitly tested for effects of community size (drift) and distance to source habitat (dispersal) on soil microarthropod community structure found evidence for both independent and interacting effects (Hoyle 2004; Åström and Bengtsson 2011). Yet, most metacommunity analyses have not explicitly quantified drift and have assumed independent effects for selection and dispersal limitation (Cottenie 2005; Hanson et al. 2012; Soininen 2016). Our results support this assumption for the conditions we studied. Perhaps interactions are only relevant at wider environmental or geographic extents. For instance, species environmental responses of aquatic invertebrates were weaker in tropical than in boreal streams, with community size being five times larger in the latter (Siqueira et al. 2020). Likewise, drift may be relatively stronger in tropical soil animal communities given their lower density (Takeda and Abe 2001), which might account for the relatively weak selective effects detected here.

Several caveats should be considered. First, it is difficult to infer causality from observational data. Accordingly, we focused on non-overlapping predictions from higher-level ecological processes (MacArthur and Wilson 1967; Hubbell 2001; Vellend 2016; Waller et al. 2018) and applied a modelling framework that has been shown by simulation to reliably infer such processes under known conditions (Ovaskainen et al. 2019; Sydenham et al. 2019). Yet, experiments will be ultimately required to validate our interpretations. Second, important predictors can always go unmeasured, especially regarding environmental variables and traits. However, as predictors related to dispersal and drift accounted for most of the variation in species occurrence, adding predictors is unlikely to change this result. Third, we focused on species occurrence rather than abundance, but the latter is harder to predict. For instance, neutral theory predicts that both equilibrium species abundance and its variance should increase with community size, making average trends less discernible (Hubbell 2001). It is possible that factors other than the ones analyzed here affect local abundance once species have established. Lastly, rare species probably looked even rarer due to imperfect detection. This could bias the estimated distance to the nearest site occupied by a species. Yet, it has been shown that rare species contribute little to observed multivariate patterns in species occurrence (Franklin et al. 2013), and simulations suggest that ecological relationships can be reasonably recovered despite imperfect detection (Barker et al. 2018; Yamaura et al. 2019). The fact that analyses excluding singletons provided similar results corroborates that overall patterns are robust to variability in rare species.

Our study suggests that dispersal limitation is the major driver of oribatid species occurrence probability over a landscape in central Amazonia, although dispersal could still connect local communities up to a few kilometres, possibly by passive dispersal. By contrast, drift- and especially selection-related predictors accounted for little variation in occurrence probability. Our results also challenge the expectation that higher-level ecological processes should interact, supporting instead the assumption of additive effects typical of variance partitioning methods. Overall, the high predictive power of distance to nearest source despite variation in species environmental responses suggests that dispersal limitation renders species ecologically equivalent at the landscape level, possibly contributing to the maintenance of metacommunity diversity.

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Author contributions PACLP and EF conceived the ideas and designed methodology; EF and RAN collected the data; PACLP analysed the data; PACLP led the writing of the manuscript. All authors contributed critically to the drafts and gave final approval for publication.

Data availability statement All data used in this manuscript are available from the figshare repository (Pequeno et al. 2021).

Declarations

Conflict of interest The authors declare that they have no conflict of interest.

Ethical approval All applicable institutional and/or national guidelines for the care and use of animals were followed.

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